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Hosted Control Planes

Overview

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Hosted Control Plane (HCP) is a control-plane topology. Each hosted cluster has its own control plane, and multiple hosted control planes run as workloads on a management cluster. In ACP, HCP is implemented through Kamaji (`TenantControlPlane`).

HCP is a Technology Preview intended only for non-production proof-of-concept (POC) evaluation. Disconnected environments are supported. HCP supports only traditional operating systems; Alauda OS is not supported. For installation and operation tasks within that scope, follow the HCP guidance below.

Note

Because Hosted Control Plane releases on a different cadence from Alauda Container Platform, the Hosted Control Plane documentation is now available as a separate documentation set at [Hosted Control Plane ↗](#).